

Supply station exit port details

The following picture shows the structure of the exit port of the official supply station, which is mainly composed of the **projectile box**, the **camera**, the **exit port**, a **laser light** and **2006 Motor and its driven crank slider mechanism**.

Their roles are:

Projectile tank: Storage projectile

Camera: Transfer the livestream to the internal display of the supply station (the display directly in front of the robot)

Exit port: the exit of the projectile

laser light: two straight laser lights form an intersection point orthogonally, located at the center of the exit port, and function as a positioning

2006 Motor and its driven crank slider mechanism: control the opening and closing of the switch plate under the magazine, thus controlling the drop of the projectiles

